

Walkthrough

How to report data to IFR Industrial Robot Statistics

This version: 7 December 2023



Choose your favorite option from the following alternatives:

- 1. Submit Excel files via e-mail (statistics@ifr.org)
- 2. Upload CSV files to my.worldrobotics.org
- 3. Enter data manually on my.worldrobotics.org
- 4. Push data through API

Note: The additional surveys on "collaborative robots" and "mobile manipulators" currently require the submission of Excel files.



1 Submit Excel files via e-mail



- 1) Please tell us who the sender and contact for questions is
- 2) Columns follow IFR application (or industry) classes and offer a short definition (full definitions provided in separate document)
- 3) Rows follow IFR geography classes
- 4) There are 6 sheets, each representing one IFR industrial robot type class

Atticulated	B Industri Dany:	fx C C C C C C C C C C C C C C C C C C C	D g operations/ ot doesn't proce	E	F Contact: Phone:	G	н	1	J	к	L	М	N	0	Р
Atticulated	B n. Inductri bany:	C C C C C C C C C C C C C C C C C C C	D g operations/ t doesn't proce	E	F Contact: Phone:	G	Н	1	J	к	L	М	N	0	Р
Statistics or Comp	n Industri bany:	110 Handlin (the robo	g operations/ t doesn't proce]	Contact: Phone:	-									
Comp stallations in un	nits	110 Handlin (the robo	g operations/ t doesn't proce		Contact: Phone:										
stallations in un	nits	110 Handlin (the robo	g operations/ ot doesn't proce		Phones		1								
stallations in un	nits	110 Handlin (the robo	g operations/ of doesn't proce												
atallations in ur	nits	(the robo	ot doesn't proce	second to be here on the second	an Analata										
Articulated	nits			ss the main oper	ration directly)	it processes for the primary	operation					160 Weldir	ng and sold	ering (all n	naterials)
Articulated		frandling operations for metal <u>casting</u>	Handling operations for plastic molding	operations for stamping/for- ging/ bending	Handling operations at machine tools	Machine tending for other processes e.g. handling during assembly, handling operations during glas or	Handling operations for measurement, inspection, testing	Handling operations for palletizing	Handling operations for packaging, picking and placing	Material Handling n.e.c.	Handling operations unspecified	Arc ⊯elding	Spot ¥elding	Laser ¥elding	other ¥elding
	robots	including die- casting	also inserting operations for injection molding			orranics production or food production Robots that handle vorkpices at an external welding TCP (i.e. MIG/MAG torch or spot gun) need to be reported in the appropriate welding classification (i.e. 161 for are welding or 162 for spot velding or and shall not be counted to	triage, quality inspection, calibrating	all sectors, al kinds and sizes of pallets	e.g. operations during primary and secondary packaging	e.g. transposing, handling during sandoasting	Handling, but the exact IFR TX class is unknown				e.g. ultrasonic welding, ga welding, plasma welding
al:					0	0							0		
ope total:	EU	0	0 0	0	0	0	0	0	0	0	0	0	0	0	
tria	AT														
arus	BY														
gium/Luxembo	urg BE														
snia Herzegovin	na BA	-													
garia	BG	-													
ata ob Ropublic	CT CT														
mark	DK														
onia	EE														
land 📿	FI														
nce 🥑	FR														
many	DE														
ece	GR														
iyaiy and	HU														
and	IE														1
iel	IL.														
1	IT														
/ia	LV														
uania	LT														
to	117						1	1				1	1	1	1





IFR

1) Enter the number of installed robots in the calender year (0 may be omitted)

1 Excel files

- To assist you, the sheet computes some control sums:
- 2) The right-hand side column offers the total by geography unit across all applications/industries
- 3) The top row contains the total by application across all territories
- 4) There are sub-totals for the continents (Asia, The Americas, Europe, Africa)







Please note:

- Only **natural numbers** are allowed (no decimals or negatives)
- You can only report to lowest-level classes. You cannot report into aggregate classes (e.g. application 110 as the aggregate of all handling/machine tending applications). If you do not know the lowest level class, please use the corresponding "unspecified" class (e.g. if you know the robot is used for handling, but not the exact application, report it to class 120 "Handling operations unspecified").
- Do not alter the structure of the file as it is processed semi-automatically. That is:
 - Do not shuffle the order of the sheets
 - Do not rename sheets
 - Do not add, remove or shuffle rows or lines

When done, submit the Excel files via e-mail to statistics@ifr.org.

This is also your contact for questions.



2 Upload CSV file to my.worldrobotics.org





- **Recommended if you have a well-maintained database** of your company's robot installations that allows you to extract data compliant with IFR classes.
- Preparation (before you submit): Configure your system to export separate CSV files for each type x application and each type x industry (i.e. one CSV file corresponds to one sheet in the Excel file). Name files according to this rule:

[YYYY]_[MM]_[APPIND|APPLICATION|INDUSTRY]_[COMPANY-CODE]_[ROBOTTYPE-CODE].csv where:

[YYYY] = calender year the data refers to

[MM] = currently always 00 (double zero)

[APPIND|APPLICATION|INDUSTRY] = currently either APPLICATION or INDUSTRY

[COMPANY-CODE] = the pseudonymous assigned by IFR Statistical Dpt.

[ROBOTTYPE-CODE] = the IFR robot type code

(10 = articulated, 20 = cartesian, 30 = cylindrical, 40 = parallel, 50 = SCARA, 99 = others)

Example: 2023_00_application_A123_10.csv



- Each file contains data according to the following format:
- One line for each datapoint (i.e. one line corresponds to one cell in the Excel file)
- 1. Reporting by Applications:

[COUNTRY-CODE];[APPLICATION-CODE];[INSTALLED UNITS] Example: DE;111;10 KR;118;4

2. Reporting by Industries:

[COUNTRY-CODE];[INDUSTRY-CODE];[INSTALLED UNITS] Example:

DE;291;10 KR;162;4



[COUNTRY-CODE]: According to IFR geography classification (see documentation, no aggregate classes)

[APPLICATION-CODE]: According to IFR application classification (see documentation, no aggregate classes)

[INDUSTRY-CODE]: According to IFR industry classification (see documentation, no aggregate classes)

[INSTALLED UNITS]: Number of industrial robots newly installed in the corresponding year

- After preparing the CSV files:
- 1) Go to my.worldrobotics.org
- 2) Log in
- Use "password forgotten" if necessary.
- If you do not have an account yet, please contact IFR Stat. Dpt. (<u>statistics@ifr.org</u> or by phone)
- If you need support, please contact IFR Stat. Dpt.





- 3) Click "Dispatches" to see the "List of Dispatches" – your company's data submissions to the IFR. It is structured as follows:
- "Dispatch": The calender year of the data
- "Type": Type of dispatch (industry or application)
- do not confuse with kinematics ("robot type")
- companies reporting payloads to the German statistics will find "payloads", too.
- "Status": Status of this dispatch
 - verified and submitted to IFR
 - pending (verified but not submitted)
 - hot verified

	^						
С	O A https://my.wo	orldrobotics.org/Dispatch/over	rview		ź	×A 🖒	◙
World Robotics	🖬 Books 👻 🖪 Disp	patches 🖺 Config 🗸 🛛	Logout				_
	3	3 L	ist of Dispatche	es			
Show 10 v entri	es Search:					Download Bar	ck
Dispatch	•		Туре		≑ Status	♦ Action	\$
Dispatch Year 2023	v	Industrierobotera	Type rten nach Nennlastbereichen		♦ Status	🔶 Action 🖉 🚣	÷
Dispatch Year 2023 Year 2023	•	Industrieroboteral	Type rten nach Nennlastbereichen vots by Industry		 Status Status 		÷
Dispatch Year 2023 Year 2023 Year 2023	•	Industrieroboteral Rob Robol	Type rten nach Nennlastbereichen pots by Industry Is by Applications		 Status O O O O 	 Action ✓ 1 ✓ 1 ✓ √ 1 ✓ ✓ 1 	÷
Dispatch Year 2023 Year 2023 Year 2023 Year 2022	•	Industrieroboteral Rot Robol Industrieroboteral	Type rten nach Nennlastbereichen bots by Industry Is by Applications rten nach Nennlastbereichen		Status Status Status S S S S S S S S S S S S S S S S S S S	Action Action	÷
Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022	•	Industrieroboterai Roto Robol Industrieroboterai Roto	Type rten nach Nennlastbereichen sots by Industry Is by Applications rten nach Nennlastbereichen sots by Industry		Status St	Action Action	÷ 81 81 81 81 81
Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022		Industrierobotera Rot Robol Industrierobotera Rot Robol	Type rten nach Nenniastbereichen sols by Industry ts by Applications rten nach Nenniastbereichen oots by Industry ts by Applications		Status O		÷
Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2022	•	Industrierobotera Roto Industrierobotera Roto Robol Robol	Type rten nach Nennlastbereichen bols by Industry Is by Applications rten nach Nennlastbereichen obs by Industry Is by Applications Is by Applications		 Status O O<!--</td--><td>Action Action Action</td><td>÷</td>	Action	÷
Dispatch Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2022 Year 2021	•	Industrierobotera Roto Industrierobotera Roto Robol Robol Robol	Type rten nach Nennlastbereichen bols by Industry Is by Applications rten nach Nennlastbereichen oots by Industry Is by Applications by Applications bots by Industry		Status © 0		÷
Dispatch Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2022 Year 2021 Year 2021 Year 2021		Industrierobotera Robol Industrierobotera Robol Robol Robol Robol Robol	Type rten nach Nennlastbereichen bots by Industry Is by Applications rten nach Nennlastbereichen bots by Industry Is by Applications to by Applications bots by Industry rten nach Nennlastbereichen		Status © © © © © © © © © © © © © ° ° ° ° ° ° ° °	Action	÷
Dispatch Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2022 Year 2021 Year 2021 Year 2021 Year 2020		Industrierobotera Robo Industrierobotera Robo Robol Robol Robol Industrierobotera Industrierobotera	Type rten nach Nennlastbereichen oots by Industry is by Applications rten nach Nennlastbereichen oots by Industry is by Applications is by Applications oots by Industry rten nach Nennlastbereichen rten nach Nennlastbereichen		Status © © © © © © © © ° ° ° ° ° ° ° ° ° ° ° ° ° °	Action Action	 <

© 2023 - International Federation of Robotics, Version 4.0



- "Action": Things you can do
 - edit data in manual editor
 - upload CSV file
 - download your latest dispatch
 - verify dispatch
 - send to IFR

- Verification means that the system does the basic plausibility check

-Upon success, the symbol will switch to "send to IFR"

-Upon failure, you will receive a report about the mismatches that need to be fixed

ē	world Robotics	×	+						\sim	
\rightarrow	С	O A http:	s://my.worldrobotic	s.org/Dispatch/ov	verview			Χ _A	ŝ	ල එ
W	orld Robotics	Books 🗸	A Dispatches	L Config -	Logout					
					List of I	Dispatches				
;	Show 10 v entr	ies Sea	rch:						Downlo	Back
					_				_	
-	Dispatch	•	L	In decatering to a feat	Туре		÷	Status 🔶	Ac	tion 🔶
Ī	Dispatch Year 2023	•		Industrierobote	Type rarten nach N	ennlastbereichen	\$	Status 🔶	Ac	tion ∲ ✓ ▲ B
	Dispatch Year 2023 Year 2023 Year 2023	•		Industrierobote R	Type rarten nach N obots by Indu	ennlastbereichen stry	\$	Status 🔶	Ac	ition
	Dispatch Year 2023 Year 2023 Year 2023 Year 2022	•		Industrieroboter R Rob	Type rarten nach N obots by Indu oots by Applic. rarten nach N	ennlastbereichen stry ations ennlastbereichen	\$	Status 🔶 C C C C	Ac	tion ♦
-	Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022	•		Industrieroboter R Rot Industrieroboter	Type rarten nach N obots by Indu pots by Applic rarten nach N	ennlastbereichen stry ations ennlastbereichen stry	\$	Status ¢	Ac	tion ♦
-	Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022	V		Industrieroboter R Rob Industrieroboter R	Type rarten nach N obots by Indu oots by Applic rarten nach N obots by Indu	ennlastbereichen stry atlions ennlastbereichen stry ations	\$	Status ¢	Ac	tion ↓ / 15 ○ / 15 ○ / 15 ○ / 15 ○ / 15 ○ / 15
	Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2021			Industrierobote R Rot Industrierobote R Rot Rot	Type rarten nach N obots by Indu bots by Applic rarten nach N obots by Indu bots by Applic	ennlastbereichen stry ations ennlastbereichen stry ations ations	\$	Status ¢		1100 1100 115 115 115 115 115 115 115 115 115 115 115 115
	Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2021 Year 2021			Industrierobotei R Rot Industrierobotei R Rot Rot	Type rarten nach N obots by Indu oots by Applic rarten nach N obots by Indu oots by Applic oots by Applic	ennlastbereichen stry ations ennlastbereichen stry ations ations stry	¢	Status		* 1 B * 2 B * 2 B * 2 B * 2 B * 2 B * 2 B * 2 B * 2 B * 2 B
	Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2021 Year 2021 Year 2021 Year 2021 Year 2021 Year 2021			Industrieroboten Rot Industrieroboten Rot Rot Rot Industrieroboten	Type rarten nach N obots by Indu oots by Applic rarten nach N obots by Applic oots by Applic oots by Applic obots by Indu rarten nach N	ennlastbereichen stry ations ennlastbereichen stry ations ations stry ennlastbereichen	\$	Status		* 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 2 B * 2 B
	Dispatch Year 2023 Year 2023 Year 2023 Year 2022 Year 2022 Year 2022 Year 2022 Year 2021 Year 2021 Year 2021 Year 2021 Year 2021 Year 2021			Industrieroboter R Industrieroboter R R R R C R Ot R Ot R Ot R Ot R Ot R Ot	Type rarten nach N obots by Indu oots by Applic oots by Applic oots by Applic oots by Indu rarten nach N rarten nach N	ennlastbereichen stry atlons ennlastbereichen stry atlons atlons stry ennlastbereichen ennlastbereichen	\$	Status ¢ C C C C C C C C C C C C C C C C C C C		* 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 1 B * 2 B

© 2023 - International Federation of Robotics, Version 4.0



4) To upload your CSV files, click the upload button 🚣 for the corresponding year and dispatch type.

🗇 📑 World Robotics × + \sim $- \rightarrow c$ A https://my.worldrobotics.org/Dispatch/overview ☆ ☆ ⊠ එ ≣ World Robotics Books -🖪 Dispatches 🔒 Config 🗸 Logout List of Dispatches Download Back Show 10 v entries Search: Dispatch Туре Status Action 0 126 Year 2023 Industrieroboterarten nach Nennlastbereichen 0 0/15 Year 2023 Robots by Industry 0 0/16 Year 2023 Robots by Applications Year 2022 Industrieroboterarten nach Nennlastbereichen 0 126 . 0/15 Year 2022 Robots by Industry 0 0/16 Year 2022 Robots by Applications Year 2021 ~ 1/20 Robots by Applications Year 2021 Robots by Industry ~ 4/25 Year 2021 Industrieroboterarten nach Nennlastbereichen \checkmark 126 Year 2020 Industrieroboterarten nach Nennlastbereichen ▲ 120 First Previous 1 2 3 4 Next Last 4

© 2023 - International Federation of Robotics, Version 4.0



5) Click "Select import files" and select the CSV files according to the year and dispatch type.

- You can upload all CSV files of the same dispatch type and year at once

- The protocol will tell you if formal errors were found (i.e. wrong country codes or wrong application or industry codes)

- The system will reject files with incorrect name (see instructions for naming of files)

\rightarrow C		O A http:	s://my.worldrobotics	.org/Dispatch/ir	mportform/246	4	E 🔻 🖒	\odot	ර :
Worl	ld Robotics	Books 👻	🖪 Dispatches	<u>≰</u> Config -	Logout				
					Import	Dispatch			
Impo	ort Dispatch						Edit	Info Back	
Th You Ple	iis form enables y u can create thes ease use the pre-	ou to import a c e files automat defined codes l	complete folder of d ically by your ERP s known from the rep	iispatch files. systems. orts.					
Fin	nd a description fo	or the import file	e here.						
Ye	ar	202	23						
Co	ompany	ad	lix						
Da	ata type	Ro	bots by Industry						
	Select import file	s	5						
				© 2023 - Ir	iternational Fe	deration of Robotics, Version 4.0			

× +

🗇 📑 World Robotics





6) After uploading all data, **click the "Verify" button** It to perform the basic plausibility check.

-The total by geography class and robot type must be the same for the dispatch by application and by industry

-Upon failure, the error report will show the identified mismatches. You can fix the CSV files and upload again or click *related to make the corrections in the built-in editor.*

7) Upon success, **click** *d* **to submit** the data to IFR.

YOU'RE DONE. THANK YOU!



3 Enter data manually on my.worldrobotics.org

3 Enter data manually



- Recommended for very small companies or companies active in a limited environment (few countries, few applications, few industries) that do not want to send Excel files.
- Log in to my.worldrobotics.org, and click "dispatches" (see steps 1 to 3 in the "upload CSV" section)
- Use the pen symbol
 to open the editor

1 World Robotics	×	+							\sim		
С		s://my.worldrobotic	s.org/Dispatch/o	verview				衣公	3	(◙
World Robotics	📕 Books 👻	🖪 Dispatches	<u> C</u> onfig -	Logout							
				List of [Dispatches						
Show 10 v entri	es Sea	arch:							Download	Bac	:k
Dispatch	•			Туре		\$	Status	÷	Actio		÷
Year 2023			Industrierobote	erarten nach Ne	ennlastbereichen		0			1	i.
Year 2023			F	Robots by Indu	stry		Q		•	/	5
Year 2023			Ro	bots by Applica	ations		0		•	1	i.
Year 2022			Industrierobote	erarten nach Ne	ennlastbereichen		0			1	B)
Year 2022			F	Robots by Indu	stry		G		(1	i.
Year 2022			Ro	bots by Applica	ations		Q		•	12	J.
Year 2021			Ro	bots by Applica	ations		~		-	112	j.
Year 2021		Robots by Industry							-	100	1
Year 2021		Industrieroboterarten nach Nennlastbereichen								12	i.
Year 2020			Industrierobote	erarten nach Ne	ennlastbereichen		A			12	8
			© 2023 - In	Iternational Fe	deration of Robotics, Version 4.0	First	Previous	1 2	3 4 Ne	ext La	ist

3 Enter data manually



5+6) Choose the appropriate robot type and click "Reload" to switch to the corresponding table

7) Enter your data

Note: You can only enter data at the lowest hierarchy levels. It is not possible to enter data on aggregate levels. If your input is not accepted, it is most likely because you tried to enter data on an aggregate level.

8) When finished, click "back"

9) Verify and send to IFR as described in steps 6 and 7 in the "upload CSV" section.

ĺ	🖻 📑 World Robotics × +							\sim	-	
	→ C O A https://my.worldrobo	otics.org/Dispatch/e	edit/2464				;	本 ☆	\bigtriangledown	<u>ර</u> :
	World Robotics Books - A Dispatcher	s 🛓 Config 🗸	Logout							
	5	Ro	bots by - Mem	Industry ber adlix	/ 2023 K -				6	8
obot	t Type 10 - articulated Value In:	stallations	~						Reload	Back
	A	В	С	D	E	F	G	Н	Ι	
1		WR - WORLD	AFR - AFRICA	ZA - South Afri	ROA - Rest of A	EG - Egypt	MA - Morocco	TN - Tunisia	OAF - Other A	Afri AM -
2	000-All Industries	709	17	17	0	0	0	0		0
3	A-B-Agriculture, forestry, fishing	0	0	0	0	0	0	0		0
4	C-Mining and quarrying	0	0	0	0	0	0	0		0
5	D-Manufacturing	477	17	17	0	0	0	0		0
6	10-12-Food and beverages	0 O	0	0	0	0	0	0		0
7	13-15-Textiles	0 O	0	0	0	0	0	0		0
8	16-Wood and furniture	0 O	0	0	0	0	0	0		0
9	17-18-Paper	0 O	0	0	0	0	0	0		0
10	19-22-Plastic and chemical products	17	17	17	0	0	0	0		0
11	19-Pharmaceuticals, cosmetics	17	17	17	0	0	0	0		0
12	20-21-other chemical products n.e.c.	0 [°]	o	0	0	0	0	0		0
13	22-Rubber and plastic products (non-automotive)	0 O	o	0	0	7 0	0	0		0
14	229-Chemical products, unspecified	0 O	o	0	0	0	0	0		0
15	23-Glass, ceramics, stone, mineral products (non-auto	0	0`	0	0	0	0	0		0
16	24-28-Metal	318	0`	0	0	0	0	0		0
17	24-Basic metals	0 O	0`	0	0	0	0	0		0
18	25-Metal products (non-automotive)	216	0	0	0	0	0	0		0
19	28-Industrial machinery	102	0	0	0	0	0	0		0
20	289-Metal, unspecified	0	0	0	0	0	0	0		0
21	26-27-Electrical/electronics	5	0	0	0	0	0	0		0
22	275-Household/domestic appliances	0	0	0	0	0	0	0		0
23	271-Electrical machinery n.e.c. (non-automotive)	5	0	0	0	0	0	0		0
24	260-Electronic components/devices	0 0	0	0	0	0	0	0		0
25	261-Semiconductors LCD LED	0	0	0	0	0	0	0		0



4 Push data through API





- Recommended for power users with a well-maintained database of your company's robot installations that allows you to compile data compliant with IFR classes.
- Please contact IFR Statistical Department through your preferred means of communication as we will need to cooperate closely during the setup process.